

## DEFAULT PRIORS AND PREDICTIVE PERFORMANCE IN BAYESIAN MODEL AVERAGING, WITH APPLICATION TO GROWTH DETERMINANTS<sup>†</sup>

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### SUMMARY

Bayesian model averaging (BMA) has become widely accepted as a way of accounting for model uncertainty, notably in regression models for identifying the determinants of economic growth. To implement BMA the user must specify a prior distribution in two parts: a prior for the regression parameters and a prior over the model space. Here we address the issue of which default prior to use for BMA in linear regression. We compare 12 candidate parameter priors: the unit information prior (UIP) corresponding to the BIC or Schwarz approximation to the integrated likelihood, a proper data-dependent prior, and 10 priors considered by Fernández *et al.* (*Journal of Econometrics* 2001; **100**: 381–427). We also compare two model priors: the uniform model prior and a prior with prior expected model size 7. We compare them on the basis of cross-validated predictive performance on a well-known growth dataset and on two simulated examples from the literature. We found that the UIP with uniform model prior generally outperformed the other priors considered. It also identified the largest set of growth determinants. Copyright © 2009 John Wiley & Sons, Ltd.

### 1. INTRODUCTION

Bayesian model averaging (BMA) is now widely accepted as a principled way of accounting for model uncertainty.<sup>1</sup> Model uncertainty has played a particularly big role in economic growth research since the early 1990s, when a surge of new growth theories gave rise to a large literature that sought to evaluate the new growth determinants (see Durlauf *et al.*, 2005, for a survey). Linear regression models dominate in growth research, and here we consider BMA for this class of models. The implementation of BMA involves solving the common challenge in Bayesian statistics of specifying the prior. For BMA, the prior has two parts: a prior for the parameters of each model, and the prior probability of each model.<sup>2</sup> The implementation of BMA is, however, subject to

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<sup>1</sup> The economics literature has long recognized model uncertainty as a central problem in regression analyses in general and in growth applications in particular. The initial approach to model selection was to use stepwise regression (Efron, 1960). Leamer (1978) suggested extreme bounds analysis to account not only for within-model uncertainty, but also for between-model uncertainty, which is associated with model selection (see Levine and Renelt, 1992, for an application to growth). The BMA methodology was developed by Leamer (1978), Raftery (1988), Madigan and Raftery (1991, 1994), who coined the name, Raftery (1993), George and McCulloch (1993) and others; for a survey of its early development see Hoeting *et al.* (1999).

<sup>2</sup> See, for example, Brock and Durlauf (2001), Fernández *et al.* (hereafter FLS) (2001a), Sala-i-Martin *et al.* (2004), and Ley and Steel (2007a,b).

the challenge that it requires prior distributions over all parameters in all models, and the prior probability of each model must also be specified.

If substantial prior information is available and can readily be expressed as a probability distribution, this should be used. Often, however, the prior information is small relative to the information in the data, and then it makes sense to use a default prior. Here we address the issue of which default prior to use.

We compare 12 candidate default parameter priors and two model priors that have been advocated in the literature. We do this on the basis of cross-validated predictive performance using a well-known growth dataset and two simulated examples from the literature. Predictive performance is a natural and neutral basis for such comparisons. We evaluate the predictive mean using the mean squared error, and the entire predictive distribution, using two different scoring rules.

We found substantial support for one of the priors evaluated: the unit information prior (UIP) that corresponds to the BIC (or Schwarz) approximation for the integrated (or marginal) likelihood, combined with a uniform prior over the model space. This also turned out to favor the largest number of growth determinants.

We are not the first to compare priors for BMA in growth regressions. FLS (2001a) applied a ‘benchmark prior’ (FLS, 2001b) to the growth context, but did not include the UIP, or alternative model priors. Sala-i-Martin *et al.* (2004, hereafter SDM) compared model prior distributions but did not compare different parameter priors. Ley and Steel (2007b, hereafter LS), following Brown *et al.* (1998, 2002), introduced a hierarchical prior on the model size and integrated out the prior model size in the model averaging. They used two parameter priors that we include in our set of 12 priors below, in combination with fixed and random model priors. However, LS did not include the UIP.<sup>3</sup>

The paper is organized as follows. Section 2 reviews BMA with a focus on prior specification. Section 3 describes how we use predictive performance to compare prior settings and gives results for the growth data. Section 4 gives the results of a simulation experiment, and Section 5 concludes.

## 2. BAYESIAN MODEL AVERAGING

### 2.1. Basic Ideas

We now briefly summarize the main ideas of BMA for linear regression.<sup>4</sup> Given a dependent variable,  $Y$ , a number of observations,  $n$ , and a set of candidate regressors,  $X_1, \dots, X_p$ , the variable selection problem is to find the most effective subset of regressors. We denote by  $M_1, \dots, M_k$  the models considered, where each one represents a subset of the candidate regressors. When all possible subsets are considered,  $K = 2^p$ . Model  $M_k$  has the form  $Y = \alpha + \sum_{j=1}^{p_k} \beta_j^{(k)} X_j^{(k)} + \varepsilon$ , where  $X_1^{(k)}, \dots, X_{p_k}^{(k)}$  is a subset of  $X_1, \dots, X_p$ ,  $\beta^{(k)} = (\beta_1^{(k)}, \dots, \beta_{p_k}^{(k)})$  is a vector of regression coefficients to be estimated, and  $\varepsilon \sim N(0, \sigma^2)$  is the error term. We denote by  $\theta_k = (\alpha, \beta^{(k)}, \sigma)$  the vector of parameters in  $M_k$ .

<sup>3</sup> In addition, Durlauf *et al.* (2006, 2008), and Brock *et al.* (2003) evaluated different sets of parameter and model priors; their approaches are discussed below.

<sup>4</sup> Comprehensive surveys of BMA include Raftery *et al.* (1997), Hoeting *et al.* (1999), Clyde and George (2004), and Doppelhofer (2008).

The likelihood function of model  $M_k$ ,  $pr(D|\theta_k, M_k)$ , summarizes all the information about  $\theta_k$  that is provided by the data,  $D$ . The *integrated likelihood* (also known as the marginal likelihood) is the probability density of the data, conditional on the model  $M_k$ , which equals the likelihood times the prior density,  $pr(\theta_k|M_k)$ , integrated over the parameter space, so that

$$pr(D|M_k) = \int pr(D|\theta_k, M_k)pr(\theta_k|M_k)d\theta_k \quad (1)$$

Equation (1) follows from the law of total probability.

The integrated likelihood is the crucial ingredient in deriving the model weight for model averaging. We denote by  $pr(M_k)$  the prior probability that  $M_k$  is the correct model, given that one of the models considered is. Then, by Bayes' theorem, the *posterior model probability* of  $M_k$ ,  $pr(M_k|D)$ , is equal to the model's share of the total posterior mass:

$$pr(M_k|D) = \frac{pr(D|M_k)pr(M_k)}{\sum_{\ell=1}^K pr(D|M_{\ell})pr(M_{\ell})} \quad (2)$$

BMA obtains the *posterior inclusion probability* of a candidate regressor,  $pr(\beta_j \neq 0|D)$ , by summing the posterior model probabilities across those models that include the regressor. Posterior inclusion probabilities provide a probability statement regarding the importance of a regressor that directly addresses what is often the researcher's prime concern: 'What is the probability that the regressor has an effect on the dependent variable?'<sup>5</sup>

BMA involves averaging over all the models considered. This can be a very large number; for example, the growth dataset we consider below features 41 candidate regressors (and so  $K = 2^{41}$ , or about two trillion models). Such a vast model space involves a major computational challenge as direct evaluation is typically not feasible. In this paper we use the leaps-and-bounds method developed by Raftery (1995) for BMA, based on the all-subsets regression algorithm of Furnival and Wilson (1974). This is implemented in the BMA R package, available at <http://cran.r-project.org/> (Raftery *et al.*, 2005, 2009).

Other approaches to dealing with the large model space are the coinflip importance sampling algorithm used by SDM, and the Markov chain Monte Carlo (MCMC) sampler used by FLS. We have experimented with all three algorithms using the FLS data and found that the results from the branch-and-bound and MCMC methods were very similar, while the coinflip method took substantially more computational time and produced less precise results. In particular, the coinflip algorithm failed to explore large parts of the model space, notably including the models with the highest posterior probabilities.

## 2.2. Prior Distributions of Parameters

The implementation of BMA in linear regression is subject to the challenge that prior distributions must be specified over all parameters in all models. Prior probabilities of all models must also be

<sup>5</sup> The posterior inclusion probability will provide an answer to this question only if the regression parameters can be interpreted causally. This will not be the case if, for example, there are common causes of growth and the regressor not included in the model, or if growth affects the regressor rather than the other way round. This issue is the general one of endogeneity and causal interpretation of regression parameters, and is not specific to BMA. We do not consider it further in this paper.

specified. If the researcher has information about the parameters, ideally this should be reflected in the priors, and informative priors should be used, as was done, for example, by Jackman and Western (1994).

However, often the amount of prior information is small and the effort needed to specify it in terms of a probability distribution is large. Thus there have been many efforts to specify default priors that could reasonably be used for all such analyses. These are sometimes called ‘noninformative’ or ‘reference’ priors, but there is debate about the extent to which a prior can be totally noninformative, and so we use the term ‘default prior’ here. Priors on parameters may affect results since they may influence the integrated likelihood (1), which is a key component of the posterior model weights (2). The integrated likelihood of a model is approximately proportional to the prior density of the model parameter evaluated at the posterior mode (Kass and Raftery, 1995). Thus the prior density should be spread out enough so that it is reasonably flat over the region of the parameter space where the likelihood is substantial. However, the prior density should also be no more spread out than necessary, since increasing the spread of the prior tends to decrease the prior ordinate at the posterior mode, which decreases the integrated likelihood and may unnecessarily penalize larger models (Raftery, 1996). The priors we discuss below make this trade-off in different ways.

We focus on a set of 12 candidate default priors that have been advocated in the literature (Table I): a prior which contains about the same amount of information as a typical single observation (Kass and Wasserman, 1995; Raftery, 1995); the data-dependent prior of Raftery *et al.* (1997), which was designed to be relatively flat over the region of the parameter space supported by the data but no more spread out than necessary; and third, the 10 automatic priors used by FLS (2001b), which do not rely on input from the researcher or information in the data, but only on the sample size and the number of regressors.

The first prior that we consider is defined implicitly by the form of the approximate integrated likelihood that is used, namely:

$$\log pr(D|M_k) \approx c - \frac{1}{2}BIC_k \quad (3)$$

where

$$BIC_k = n \log(1 - R_k^2) + p_k \log(n) \quad (4)$$

In (4),  $R_k^2$  and  $p_k$  are the coefficient of determination and the number of regressors, respectively, for model  $M_k$ , and  $c$  is a constant that does not vary across models and so cancels in the model averaging.  $BIC_k$  is the Bayesian information criterion for  $M_k$ , which is equivalent to the approximation derived by Schwarz (1978) for the regression model, as shown by Raftery (1995).<sup>6</sup> The approximate integrated likelihood in (3) was the basis of the model averaging method of Raftery (1995) for linear regression, and was also used by SDM.

Raftery (1995, Section 4) showed that (3) gives an approximation to the integrated likelihood with an error that is  $O(n^{-1/2})$  when the prior for the regression parameters is multivariate normal centered at the maximum likelihood estimate with variance matrix equal to  $n$  times the inverse of

<sup>6</sup> Klein and Brown (1984) discuss an alternative derivation of BIC model weights by minimizing the Shannon information in the prior distribution.

Table I. Parameter prior structures

Prior	Specification of $g$ -prior	Comment	Source
1	Unit information prior	The prior contains information approximately equal to that contained in a single typical observation. The resulting posterior model probabilities are closely approximated by the Schwarz criterion, BIC	Kass and Wasserman (1995); Raftery (1995)
2	$g_k = p_k/n$	Prior information increases with the number of regressors in the model	FLS (2001b)
3	$g_k = p^{1/p_k}/n$	Prior information decreases with the number of regressors in the model	FLS (2001b)
4	$g = 1/\sqrt{n}$	This is an intermediate case of Prior 1 suggested by FLS where a smaller asymptotic penalty is chosen for larger models	FLS (2001b)
5	$g_k = \sqrt{p_k/n}$	This is an intermediate case of Prior 2, suggested by FLS, where prior information increases with the number of regressors in the model	FLS (2001b)
6	$g = 1/(\ln n)^3$	The Hannan–Quinn criterion. CHQ = 3 as $n$ becomes large	Hannan and Quinn (1979)
7	$g_k = \ln(p_k + 1)/(\ln n)$	Prior information decreases even slower with sample size and there is asymptotic convergence to the Hannan–Quinn criterion with CHQ = 1	Hannan and Quinn (1979)
8	$g_k = \delta\gamma^{(1/p_k)}/(1 - \delta\gamma^{(1/p_k)})$	A natural conjugate prior structure, subjectively elicited through predictive implications. $\gamma < 1$ (so that $g$ increases with $k_j$ ) and delta such that $g/(1 + g) \in [0.10, 0.15]$ (the weight of the 'prior prediction error' in the Bayes factors); for $k_j$ ranging from 1 to 15. FLS suggest covering this interval with the values of $\gamma = 0.65$ and $\delta = 0.15$	Laud and Ibrahim (1996)
9	$g = 1/p_2$	This prior is suggested by the risk inflation criterion (RIC)	Foster and George (1994)
10	$g = 1/(\max\{n, p^2\})$	The preferred prior of Fernández <i>et al.</i> (2001), a mix of Prior 9 and Prior 1	FLS (2001b)
11	$\beta \sim N(\mu, \sigma^2 V)$ $V = \sigma^2 \phi^2 (1/n X'X)^{-1}$ $v\lambda/\sigma^2 \sim \chi^2$	Data-dependent prior. $\phi = 0.85$ , $v = 2.58$ , $\lambda = 0.28$ if the $R^2$ of the full model is less than 0.9, and $\phi = 9.2$ , $v = 0.2$ , $\lambda = 0.1684$ if the $R^2$ of the full model is greater than 0.9	Raftery <i>et al.</i> (1997)
12	$g = n^{-1}$	Similar to the unit information prior, but with mean zero instead of MLE	FLS (2001b)

the observed Fisher information matrix.<sup>7</sup> This prior is much more spread out than the likelihood, and typically is relatively flat where the likelihood is substantial (Raftery, 1999). It contains the same amount of information as would be contained on average in a single observation and so, following Kass and Wasserman (1995), we call it the unit information prior (UIP). Because of

<sup>7</sup> It follows further from the results of Kass and Wasserman (1995) that for any pairwise model comparison the ratio of posterior model probabilities resulting from the use of (3) closely approximates the ratio of posterior model probabilities with a prior that is the same except that its mean is equal to zero instead of the MLE, again with error of order  $O(n^{-1/2})$ .

its simplicity and intuitive appeal, we use the UIP as a baseline, and we compare other proposed default priors to it.<sup>8</sup>

Next, we consider 10 automatic priors considered by FLS (2001b) of the following form:

$$p(\alpha|M_k) \propto 1 \quad (5)$$

$$p(\sigma|M_k) \propto 1/\sigma \quad (6)$$

$$\beta^{(k)}|\sigma, M_k \sim N(0, \sigma^2(g_k Z^{(k)'} Z^{(k)})^{-1}) \quad (7)$$

where  $Z^{(k)}$  is the  $n \times p_k$  matrix consisting of the  $p_k$  regressors included in  $M_k$ , each one centered by subtracting its mean. The prior (7) for  $\beta^{(k)}$  is based on Zellner's (1986)  $g$ -prior, but the overall prior (5)–(7) was proposed by FLS (2001b), who showed that it leads to analytical integrated likelihoods. The value of  $g$  scales the reciprocal of the variance of the parameter prior. Values of  $g$  that are closer to zero imply priors that are less informative, and  $g = 1$  implies that prior information and data information are weighted equally in the posterior distribution. Different automatic priors result from different choices of  $g_k$ , as listed in Table I.

The choice  $g = 1/n$  (Prior 12 in Table I) has the same variance as the UIP, but its mean is at zero instead of the MLE. Alternatives are Prior 4,  $g = \sqrt{1/n}$ , which attributes a smaller asymptotic penalty than BIC, and Prior 2,  $g_k = p_k/n$ , where prior information increases with the number of regressors in the model. Other priors suggested by FLS (2001b) correspond to previous proposals: Priors 6 and 7 in Table I are versions of the Hannan and Quinn criterion (Hannan and Quinn, 1979), and Prior 9,  $g_k = 1/p^2$ , corresponds to the risk inflation criterion (RIC) of Foster and George (1994), designed to take account of the number of candidate regressors. Prior 10 is the preferred prior of FLS (2001b), developed on the basis of their experiments with their priors. It is composed of either the RIC-based prior (Prior 9) or Prior 12, depending on the number of observations and regressors in the particular dataset. For the datasets considered in this paper, Prior 10 is identical to Prior 9.

An alternative class of data-dependent priors can be viewed as approximating the subjective prior of an experienced researcher. Clearly, if such knowledge can be readily elicited in the form of a probability distribution, it should be introduced into the analysis. Raftery *et al.* (1997) specified conjugate data-dependent priors that are as concentrated as possible, subject to being reasonably flat over the region of parameter space where the likelihood is not negligible. Their prior (Table I, Prior 11) is specified by four hyperparameters that are explained in Table I. Another such data-dependent prior is based on Laud and Ibrahim (1996) (Table I, Prior 8) who specified  $g = \delta\gamma^{1/p_j}/(1 - \delta\gamma^{1/p_j})$ . Given FLS's suggestions for  $\gamma$  and  $\delta$ , they mention that model comparisons based on the resulting log integrated likelihood can roughly be compared to those based on the Akaike information criterion (AIC) (Akaike, 1974).

<sup>8</sup> It could be argued that this prior depends on the data and so is not a valid prior for Bayesian analysis. However, we use it here as an approximation to the prior information of an analyst who knows something, but not a great deal, about the problem at hand. For estimating a population mean, its use implies roughly that the analyst knows at least that the mean is within the range of the data, and it seems likely that anyone analyzing data about the problem would know at least that much (Raftery, 1999). Wasserman (2000) showed that data-dependent priors can actually improve predictive performance. FLS (2001b) point out a common criticism of data-dependent priors, namely that the posterior distribution can no longer be interpreted as a conditional distribution given the observables.

### 2.3. Model Priors

The most common model prior in the literature is the uniform distribution that assigns equal prior probability all models, so that  $pr(M_k) = 1/K$  for each  $k$ . This was suggested first by Raftery (1988) and, for linear regression models, by George and McCulloch (1993). Hoeting *et al.* (1999) cite the extensive evidence that supports the good performance of the UIP, since the integrated likelihood on the model space is often concentrated enough for the results to be insensitive to moderate deviations from the uniform prior.

We also consider the more general model prior proposed by Mitchell and Beauchamp (1988), namely

$$pr(M_k) = \prod_{j=1}^p \pi_j^{\delta_{kj}} (1 - \pi_j)^{1-\delta_{kj}} \quad (8)$$

where  $\delta_{kj} = 1$  if  $X_j$  is included in  $M_k$  and 0 otherwise. In (8),  $\pi_j$  is the prior probability that  $X_j$  is included in the model, and it is usually assumed that  $\pi_j = \pi$  for  $j = 1, \dots, p$ . When  $\pi = 0.5$ , (8) reduces to the uniform prior. The general prior in (8) has been widely used, for example by George and McCulloch (1993), Madigan and Raftery (1994) and SDM. SDM assumed  $\pi = 7/p$  in growth applications, yielding a prior expected model size of  $\pi p = 7$ . Following Brown *et al.* (1998, 2002), LS suggested that  $\pi$  itself be a random variable drawn from a Beta  $\left(1, \frac{1-\pi}{\pi}\right)$  distribution. They evaluated parameter Priors 9 and 12 with fixed and random  $\pi$ . We adopt (8) and examine growth determinants as well as their predictive performance for a range of fixed model priors. We also compare our results with those in LS with fixed and random  $\pi$ .<sup>9</sup>

There is a tradeoff between the prior inverse variance parameter  $g$  and the prior inclusion probabilities,  $\pi_j$  in (8), pointed out by Taplin and Raftery (1994, Section 5.2) in a slightly different context, and also revealed by computations in LS. We now give a theoretical explanation for this, taking  $\pi_j = \pi$  for  $j = 1, \dots, p$  for easier exposition.

Comparing the posterior probabilities for a given model in (2) for different priors, Kass and Raftery (1995) showed that an increase in the prior standard deviation by a factor  $c$  is approximately equivalent to a reduction in the prior odds for an increase in the model size by an additional variable, by the same factor of  $c$ .

Using the approximation of Kass and Raftery (1995, equation 14), it can be shown that for two priors,  $A$  and  $B$ , with associated prior scale factors,  $g_A$ ,  $g_B$ , and prior inclusion probabilities,  $\pi_A$ ,  $\pi_B$ , the posterior odds for one regression model against an alternative regression model with one additional regressor are approximately equal when the priors satisfy

$$\frac{g_A}{g_B} = \left[ \frac{\pi_B (1 - \pi_A)}{\pi_A (1 - \pi_B)} \right]^2 \quad (9)$$

This shows the nature of the tradeoff between the prior scale factor and the prior inclusion probability: a change in  $\pi$  has approximately the same effect as the change in  $g$  given by equation (9).

<sup>9</sup> Like most workers in this area, we use the independent model priors specified by (8). However, non-independent default priors have been proposed as well. George (1999, 2001) and Durlauf *et al.* (2008) introduced dependent model priors that account for the correlation structure of the regressors. Brock *et al.* (2003) proposed tree-structured priors that are based on substantive knowledge of context.

### 3. DETERMINING GROWTH DETERMINANTS

Since economic growth is the fundamental driver of living standards, it is of great interest to economists and policymakers alike to identify which of the numerous theories proposed receive support from the data and which determinants have a significant effect on growth. Attempts to identify robust growth determinants date back to Levine and Renelt (1992), who used extreme bounds analysis. Formal BMA analysis was conducted by Brock and Durlauf (2001), FLS (2001a) and SDM (2004). The dataset used across studies always contains a core of at least 41 candidate regressors, motivated by Sala-i-Martin (1997) and FLS (2001a). We base our growth analysis on the same dataset that FLS kindly shared with us.

#### 3.1. Effects of Parameter Priors on Growth Determinants

For datasets with small numbers of observations such as our growth dataset with 72 observations, priors can play an important role. As can be seen in Figure 1, the precisions of the parameter priors vary widely; for example, the information contained in Prior 7 is three orders of magnitude greater than that in the FLS-preferred prior. It thus seems possible that the BMA results would vary considerably between priors.

Table II reports the BMA posterior inclusion probabilities for all 12 prior distributions applied to the growth dataset. Posterior inclusion probabilities and the number of regressors that exhibit evidence of an effect on growth vary substantially across priors. The number of regressors whose inclusion probability exceeds 50% ranges from a low of seven regressors (Priors 5, 7, and 11) to a high of 22 regressors (Prior 1). Recall that, apart from the UIP, the prior distributions are all centered at zero and that Priors 5 and 7 have small prior variance that emphasizes the zero expected mean, while the variance of Prior 11 has the largest variance in the sample, which to emphasizes uncertainty (see Figure 1). Priors 5, 7, and 11 contain strong information *against* a large effect, and the information contained in the data is too weak to overwhelm that prior. As the priors over the parameter space become spread out enough to include those regions where the likelihood is large, the number of regressors that exhibit an effect increases. Figure 1 shows that both more diffuse and more precise priors (Priors 11, 7, and 5) lead to a decline in the integrated likelihood, thus reducing the number of regressors showing an effect.

Figure 2 shows scatterplots of posterior inclusion probabilities generated by the various priors against Prior 1. Since Prior 1 was the most optimistic, with 22 candidate regressors showing an effect in Table II, it is no surprise that most of the points in the scatterplots lie above the 45° line, indicating higher posterior inclusion probabilities under Prior 1 than under other priors. The scatterplots also show how the differences between Prior 1 and alternative priors increase as the implied  $g$ -prior diverges. Priors 1, 6, and 12 yielded similar results, but most other priors showed differing effects implied by the priors.

#### 3.2. Combined Effects of Parameter and Model Priors on Growth Determinants

SDM advocated using a Mitchell–Beauchamp prior (8) with  $\pi = 7/p$ , equivalent to a prior expected model size of 7 regressors. We combined this model prior with the 12 parameter priors considered, and the results are shown in Table III. As expected, this leads to smaller models than the uniform model prior, ranging from 3 to 10 effective regressors with posterior inclusion



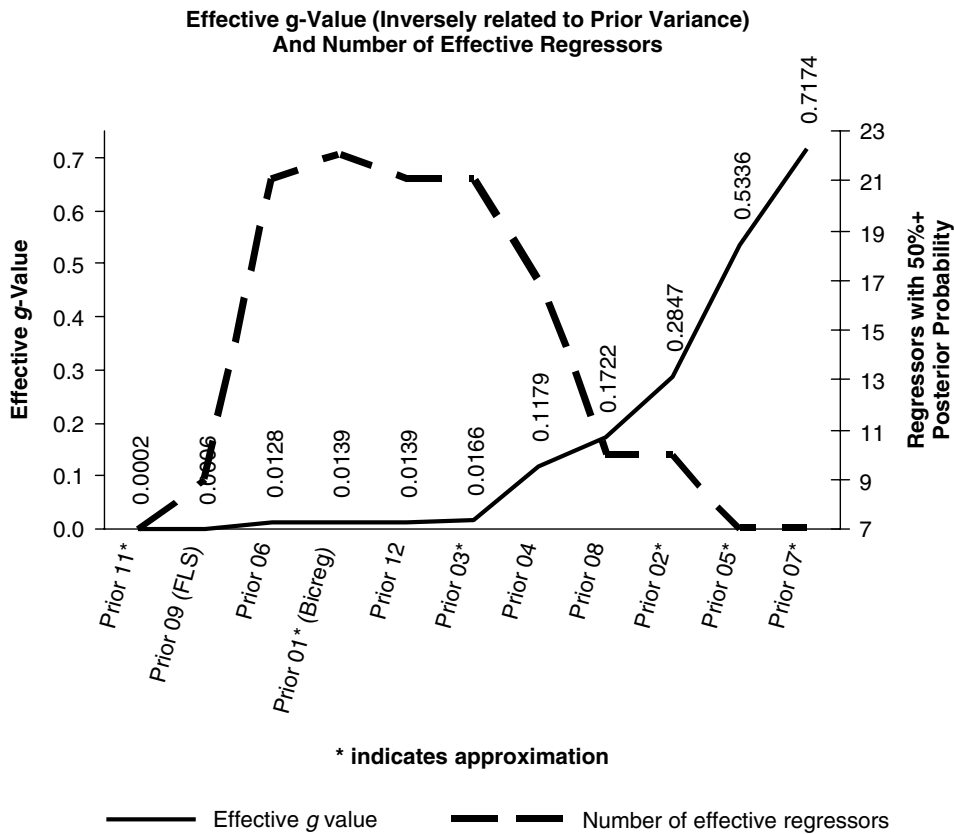


Figure 1. Effective  $g$ -value (inversely related to prior variance) and number of effective regressors. (1) When priors depend on the exact model size,  $p_k$ , Figure 1 approximates the prior using the expected model size. Priors 11 and 1 are not exact  $g$ -priors, so the  $g$ -value is also an approximation. (2) Priors 9 and 10 are identical in the growth context

probabilities above 50%. Again the priors with intermediate variance have a slightly larger number of regressors (Priors 3, 4, and 12), and as before the number of regressors that exhibit an effect declines as the prior variance become large (Priors 6 and 9). The Mitchell–Beauchamp model prior has the least impact on Prior 11; for this prior, the rule of law variable loses significance but otherwise the results are identical to Table II.

The image plots in Figure 3, produced by the BMA R package, highlight how different the models are over which the various priors average. The figure shows models used in the averaging process on the horizontal axis. Each model’s posterior probability is indicated by its horizontal width. Posterior means are indicated as positive (darker shading) or negative. Comparing Figure 3(a) and (c), we see that the model prior with prior expected model size 7 favors growth models with fewer variables. In addition, the image plots highlight that, while the procedure averages over the same number of models, many more models receive negligible weight if the model size is presumed to be small. On the other hand, we note the similarity between Figure 3(b) and (c), which feature two very different model and parameter priors. This similarity

Table II. Posterior inclusion probabilities across parameter priors: model prior = uniform (growth dataset)

	Priors arranged by effective <i>g</i> -value (increasing left to right)										
	Prior 11	9 (FLS)	Prior 6	Prior 1	Prior 12	Prior 3	Prior 4	Prior 8	Prior 2	Prior 5	Prior 7
Confucius	<b>99.5</b>	<b>99.9</b>	<b>100.0</b>	<b>100.0</b>	<b>100.0</b>	<b>100.0</b>	<b>100.0</b>	<b>100.0</b>	<b>99.9</b>	<b>99.2</b>	<b>98.5</b>
GDPsh560	<b>99.9</b>	<b>99.9</b>	<b>100.0</b>	<b>100.0</b>	<b>100.0</b>	<b>100.0</b>	<b>100.0</b>	<b>100.0</b>	<b>100.0</b>	<b>99.5</b>	<b>98.5</b>
Life	<b>96.5</b>	<b>96.4</b>	<b>99.9</b>	<b>100.0</b>	<b>100.0</b>	<b>99.9</b>	<b>99.8</b>	<b>98.6</b>	<b>96.4</b>	<b>93.1</b>	<b>90.9</b>
RuleofLaw	47.2	<b>64.0</b>	<b>99.6</b>	<b>100.0</b>	<b>99.6</b>	<b>99.6</b>	<b>98.3</b>	<b>93.0</b>	<b>69.3</b>	<b>57.3</b>	<b>56.6</b>
SubSahara	<b>74.8</b>	<b>83.8</b>	<b>99.9</b>	<b>100.0</b>	<b>100.0</b>	<b>100.0</b>	<b>99.7</b>	<b>97.5</b>	<b>86.3</b>	<b>80.2</b>	<b>79.6</b>
EquipInv	<b>99.0</b>	<b>96.8</b>	<b>98.3</b>	<b>99.9</b>	<b>98.4</b>	<b>98.3</b>	<b>95.6</b>	<b>88.8</b>	<b>94.4</b>	<b>95.3</b>	<b>95.2</b>
Hindu	3.2	10.3	<b>96.6</b>	<b>99.9</b>	<b>97.0</b>	<b>96.8</b>	<b>88.7</b>	42.8	16.7	15.0	18.5
HighEnroll	0.3	0.7	<b>93.4</b>	<b>99.8</b>	<b>94.0</b>	<b>93.5</b>	<b>78.1</b>	2.8	2.1	3.9	7.2
LabForce	0.4	1.3	<b>94.5</b>	<b>99.8</b>	<b>95.0</b>	<b>94.6</b>	<b>81.6</b>	11.6	3.9	5.6	9.2
EthnoLFrac	0.5	1.3	<b>90.8</b>	<b>99.3</b>	<b>91.4</b>	<b>90.8</b>	<b>74.6</b>	7.2	3.3	4.8	8.0
Mining	28.0	38.5	<b>96.4</b>	<b>99.2</b>	<b>96.5</b>	<b>96.4</b>	<b>93.3</b>	<b>74.7</b>	49.1	43.4	44.1
LatAmerica	9.2	13.4	<b>79.5</b>	<b>97.2</b>	<b>80.3</b>	<b>79.4</b>	<b>61.0</b>	30.2	17.7	17.5	19.1
SpanishCol	0.0	0.1	<b>67.6</b>	<b>94.6</b>	<b>68.7</b>	<b>67.3</b>	42.3	2.0	0.5	1.1	2.4
FrenchCol	0.3	0.2	<b>65.4</b>	<b>93.9</b>	<b>66.5</b>	<b>65.1</b>	39.4	0.0	0.3	1.0	2.2
BritCol	0.0	0.0	<b>64.7</b>	<b>93.6</b>	<b>65.8</b>	<b>64.4</b>	38.7	0.7	0.2	0.6	1.8
PrSc	19.3	12.0	<b>72.2</b>	<b>90.7</b>	<b>72.8</b>	<b>72.2</b>	<b>58.0</b>	8.1	14.1	16.1	17.5
CivilLib	5.2	3.3	<b>66.8</b>	<b>85.7</b>	<b>67.5</b>	<b>66.7</b>	<b>51.2</b>	3.7	4.4	5.4	7.1
NEquipInv	28.8	49.3	<b>71.3</b>	<b>85.6</b>	<b>71.7</b>	<b>71.3</b>	<b>66.6</b>	<b>82.1</b>	<b>52.4</b>	41.1	40.3
English.	0.5	1.1	<b>58.0</b>	<b>84.5</b>	<b>58.9</b>	<b>57.7</b>	36.7	2.7	2.2	2.4	3.5
OutwarOr	0.0	0.0	<b>51.2</b>	<b>82.8</b>	<b>52.2</b>	<b>51.0</b>	31.4	0.7	0.2	0.6	1.7
BIMktPm	5.1	12.2	<b>63.8</b>	<b>72.5</b>	<b>63.9</b>	<b>64.1</b>	<b>67.6</b>	45.4	19.6	17.4	19.9
Muslim	<b>66.9</b>	<b>68.3</b>	44.3	<b>60.9</b>	44.4	44.4	49.4	<b>54.9</b>	<b>66.5</b>	<b>60.3</b>	<b>56.1</b>
Buddha	4.1	10.2	19.5	36.5	19.7	19.7	21.5	31.1	13.4	10.6	11.4
EcoOrg	34.2	<b>56.6</b>	39.5	35.6	39.2	39.7	<b>50.1</b>	<b>88.7</b>	<b>61.0</b>	47.3	45.2
X.PublEdu	0.0	0.2	17.9	13.3	17.8	18.1	19.4	1.5	0.6	1.1	2.0
PolRights	2.0	2.7	16.4	12.4	16.5	16.5	14.6	10.1	4.5	4.4	4.8
Protestants	35.5	<b>51.5</b>	25.7	11.7	25.2	26.0	41.7	<b>81.3</b>	<b>56.8</b>	47.7	46.4
WarDummy	1.1	0.9	6.2	11.7	6.4	6.3	3.9	0.8	1.2	1.8	2.0
Age	0.4	0.7	14.6	11.4	14.7	14.7	12.2	3.3	1.3	1.7	2.3
RFEXDist	1.8	2.0	4.6	9.6	4.7	4.7	4.0	0.6	2.6	3.3	3.4
Catholic	4.1	8.7	3.5	7.5	3.5	3.6	7.1	20.3	11.0	8.3	8.2
Popg	0.2	0.3	2.2	3.6	2.2	2.3	2.2	0.2	0.5	0.5	0.5
PrExports	2.2	2.5	1.2	2.8	1.2	1.2	2.1	5.9	3.7	3.0	2.8
Foreign	0.5	0.3	0.7	2.0	0.7	0.7	0.4	0.0	0.2	0.6	0.7
Jewish	0.0	0.0	0.8	1.3	0.8	0.8	0.7	0.0	0.0	0.0	0.1
std.BMP	0.0	0.0	0.6	1.3	0.6	0.6	0.4	0.0	0.0	0.0	0.0
Area	0.0	0.0	0.8	1.1	0.9	0.9	1.1	0.0	0.1	0.1	0.2
Work. pop.	0.4	0.2	0.3	1.1	0.3	0.3	0.2	0.0	0.2	0.6	0.8
AbsLat	0.6	0.5	1.2	1.0	1.2	1.2	1.8	0.3	0.7	0.9	1.0
YrsOpen	<b>57.8</b>	40.9	1.2	1.0	1.1	1.2	3.4	15.3	37.3	44.2	42.4
Rev.Coup	0.1	0.2	0.4	0.7	0.4	0.4	0.7	1.1	0.5	0.4	0.4
No. of relevant regressors	7	9	21	22	21	21	17	11	10	7	7

Note: Posterior inclusion probabilities that exceed 50% are in bold font (Jeffreys, 1961). Priors 9 and 10 are identical in the growth context.

was first observed for these specific priors by Masanjala and Papageorgiou (2005). LS describe the similarity between the FLS uniform prior and Prior 1 with prior model size 7 as arising ‘mostly by accident’ and discuss specific parameter constellations that generate similar posterior probabilities. We showed in Section 2.3 that in fact this similarity has a theoretical explanation.

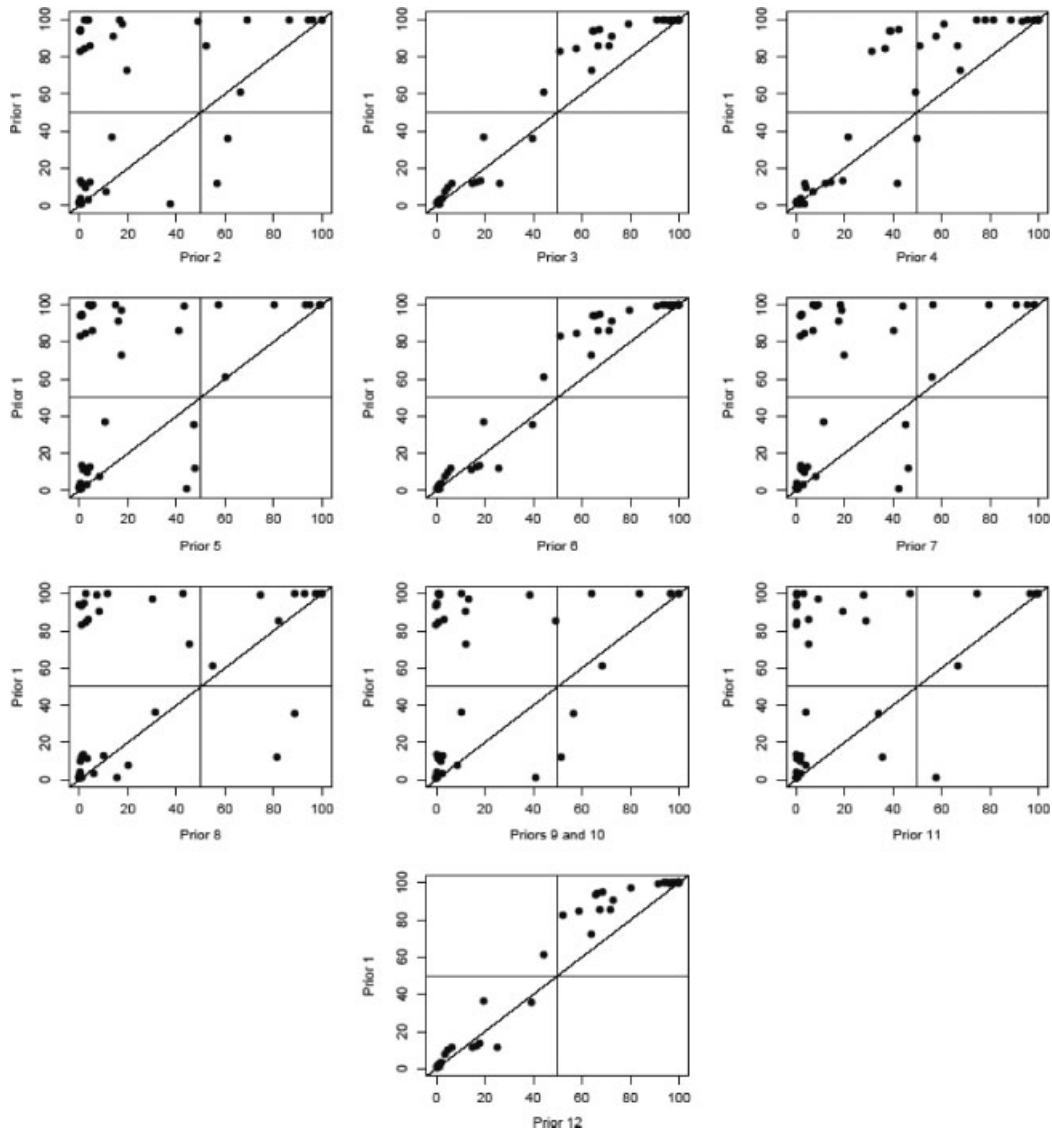


Figure 2. Correlation of posterior inclusion probabilities across parameter priors (growth dataset). Priors 9 and 10 are identical in the growth context

For the FLS dataset with  $n = 72$  and  $p = 41$ , the FLS benchmark parameter prior implies  $g_A = 1/p^2$ , combined with the uniform model prior,  $\pi_A = \frac{1}{2}$ , in the notation of (9). When  $g_B = 1/n$  as in the case of Prior 1, used by SDM, equation (9) holds when the prior inclusion probability is  $\pi_A = 7.03/p$ , so that the prior expected model size is 7.03. It is therefore not surprising that for the SDM suggested prior expected model size of 7 the priors recommended by SDM and FLS yield similar results for the growth dataset, although they are based on very different parameter and

Table III. Posterior inclusion probabilities across parameter and model priors: uniform model prior column 1, all other columns: prior model size = 7 (as in Sala-i-Martin *et al.*, 2004) (growth dataset)

Prior 1 Model prior: uniform	Priors arranged by effective $g$ -value (increasing left to right)											
	Prior 11	Prior 9	Prior 6	Prior 1	Prior 12	Prior 3	Prior 4	Prior 8	Prior 2	Prior 5	Prior 7	
Confucius	<b>100.0</b>	<b>92.0</b>	<b>95.8</b>	<b>99.7</b>	<b>99.9</b>	<b>99.7</b>	<b>99.7</b>	<b>98.7</b>	<b>97.2</b>	<b>96.5</b>	<b>87.1</b>	<b>84.8</b>
GDPsh560	<b>100.0</b>	<b>91.6</b>	<b>91.7</b>	<b>99.8</b>	<b>100.0</b>	<b>99.8</b>	<b>99.8</b>	<b>99.0</b>	<b>97.3</b>	<b>96.8</b>	<b>71.8</b>	<b>50.1</b>
Life	<b>100.0</b>	<b>79.5</b>	<b>77.4</b>	<b>94.8</b>	<b>97.8</b>	<b>94.9</b>	<b>94.8</b>	<b>90.2</b>	<b>84.9</b>	<b>82.0</b>	48.8	30.8
RuleofLaw	<b>100.0</b>	16.5	16.9	49.4	<b>68.6</b>	<b>50.2</b>	<b>50.4</b>	37.0	29.2	21.5	12.3	8.2
SubSahara	<b>100.0</b>	<b>61.8</b>	<b>60.4</b>	<b>76.5</b>	<b>86.3</b>	<b>76.9</b>	<b>77.0</b>	<b>70.1</b>	<b>66.1</b>	<b>62.9</b>	48.5	35.1
EquipInv	<b>99.9</b>	<b>99.5</b>	<b>99.4</b>	<b>98.2</b>	<b>99.2</b>	<b>98.1</b>	<b>98.0</b>	<b>98.5</b>	<b>98.7</b>	<b>99.0</b>	<b>98.5</b>	<b>97.9</b>
Hindu	<b>99.9</b>	0.0	0.0	4.8	9.6	5.0	5.1	2.3	1.1	0.1	0.0	0.0
HighEnroll	<b>99.8</b>	0.1	0.1	0.1	1.0	0.1	0.1	0.1	0.1	0.1	0.8	1.2
LabForce	<b>99.8</b>	0.0	0.0	0.3	1.5	0.3	0.3	0.1	0.0	0.0	0.0	0.0
EthnoLFrac	<b>99.3</b>	0.2	0.2	0.4	0.9	0.5	0.5	0.4	0.4	0.4	0.5	0.3
Mining	<b>99.2</b>	4.1	6.9	31.2	33.7	31.8	32.2	25.8	19.6	12.0	3.8	1.7
LatAmerica	<b>97.2</b>	4.7	6.0	11.2	11.1	11.4	11.6	11.6	10.9	9.3	6.1	3.9
SpanishCol	<b>94.6</b>	0.0	0.0	0	0.0	0.0	0.0	0.0	0.0	0.0	0.0	0.0
FrenchCol	<b>93.9</b>	0.3	0.3	0.3	0.0	0.3	0.3	0.6	0.7	0.7	0.3	0.1
BritCol	<b>93.6</b>	0.0	0.0	0	0.0	0.0	0.0	0.0	0.0	0.0	0.0	0.0
PrSc	<b>90.7</b>	6.6	7.8	13.3	8.0	13.3	13.5	14.6	13.6	11.5	6.5	4.8
CivilLib	<b>85.7</b>	1.0	1.2	3.2	2.2	3.2	3.3	3.3	2.9	2.1	0.6	0.4
NEquipInv	<b>85.6</b>	3.2	5.6	34.7	<b>56.2</b>	35.4	35.5	23.0	16.6	9.8	5.2	4.1
English	<b>84.5</b>	0.0	0.0	0.8	0.1	0.8	0.9	0.7	0.4	0.1	0.1	0.3
OutwarOr	<b>82.8</b>	0.0	0.0	0	0.1	0.0	0.0	0.0	0.0	0.0	0.1	0.3
BIMktPm	<b>72.5</b>	0.1	0.3	6.8	10.0	7.1	7.3	4.6	2.7	0.8	0.1	0.0
Muslim	<b>60.9</b>	21.5	29.2	<b>65.6</b>	<b>69.1</b>	<b>65.9</b>	<b>65.8</b>	<b>56.5</b>	46.9	37.2	13.0	7.2
Buddha	36.5	2.3	2.6	5.9	11.8	6.1	6.2	3.8	3.1	2.0	9.6	13.8
EcoOrg	35.6	4.7	7.6	40.7	<b>61.9</b>	41.6	41.7	27.4	19.7	11.9	6.2	5.0
X.PublEdu	13.3	0.0	0.0	0	0.2	0.0	0.0	0.0	0.0	0.0	0.0	0.0
PolRights	12.4	0.3	0.5	1.9	0.8	1.9	2.0	2.0	1.7	1.2	0.4	0.5
Protestants	11.7	16.8	21.3	40.7	<b>51.8</b>	41.3	41.5	32.6	27.4	21.4	24.9	25.6
WarDummy	11.7	0.8	0.9	1.2	0.0	1.2	1.2	1.9	2.1	1.9	1.3	0.7
Age	11.4	0.4	0.6	0.6	0.1	0.6	0.7	0.9	1.1	1.0	1.8	2.0
RFEXDist	9.6	1.2	1.6	2.5	0.0	2.5	2.6	3.3	3.3	2.6	3.8	4.8
Catholic	7.5	0.6	1.1	5.3	9.0	5.5	5.5	3.3	2.3	1.4	1.9	1.6
Popg	3.6	0.0	0.0	0.2	0.0	0.2	0.3	0.2	0.1	0.0	0.1	0.2
PrExports	2.8	0.1	0.1	1.8	1.3	1.9	1.9	1.4	0.9	0.3	0.5	0.5
Foreign	2.0	0.6	0.9	0.6	0.0	0.6	0.6	1.1	1.3	1.5	1.0	0.7
Jewish	1.3	0.0	0.0	0	0.0	0.0	0.0	0.0	0.0	0.0	0.1	0.2
std.BMP	1.3	0.0	0.0	0	0.0	0.0	0.0	0.0	0.0	0.0	0.4	0.8
Area	1.1	0.0	0.0	0	0.0	0.0	0.0	0.0	0.0	0.0	0.1	0.3
Work.Pop	1.1	1.1	1.2	0.5	0.1	0.4	0.5	1.0	1.5	1.7	2.2	2.2
AbsLat	1.0	0.2	0.3	0.6	0.0	0.6	0.6	0.8	0.8	0.7	0.2	1.0
YrsOpen	1.0	<b>59.8</b>	<b>63.0</b>	<b>52.4</b>	38.0	<b>51.8</b>	<b>51.7</b>	<b>59.2</b>	<b>61.0</b>	<b>63.5</b>	49.1	38.2
Rev.Coup	0.7	0.0	0.0	0.1	0.0	0.1	0.1	0.1	0.0	0.0	0.0	0.0
Relevant regressors	22	6	6	7	10	8	8	7	6	6	3	3

Note: Posterior inclusion probabilities that exceed 50% are in bold font (Jeffreys, 1961). Priors 9 and 10 are identical in the growth context. Priors are arranged by effective  $g$ -value (see Figure 1).

model priors. Note that this similarity depends crucially on the number of candidate regressors in the dataset,  $p$ . Subjective priors that favor small models thus achieve their aim by punishing larger models (Figure 3(c)) or by increasing the prior variance on each individual parameter (Figure 3(b)).

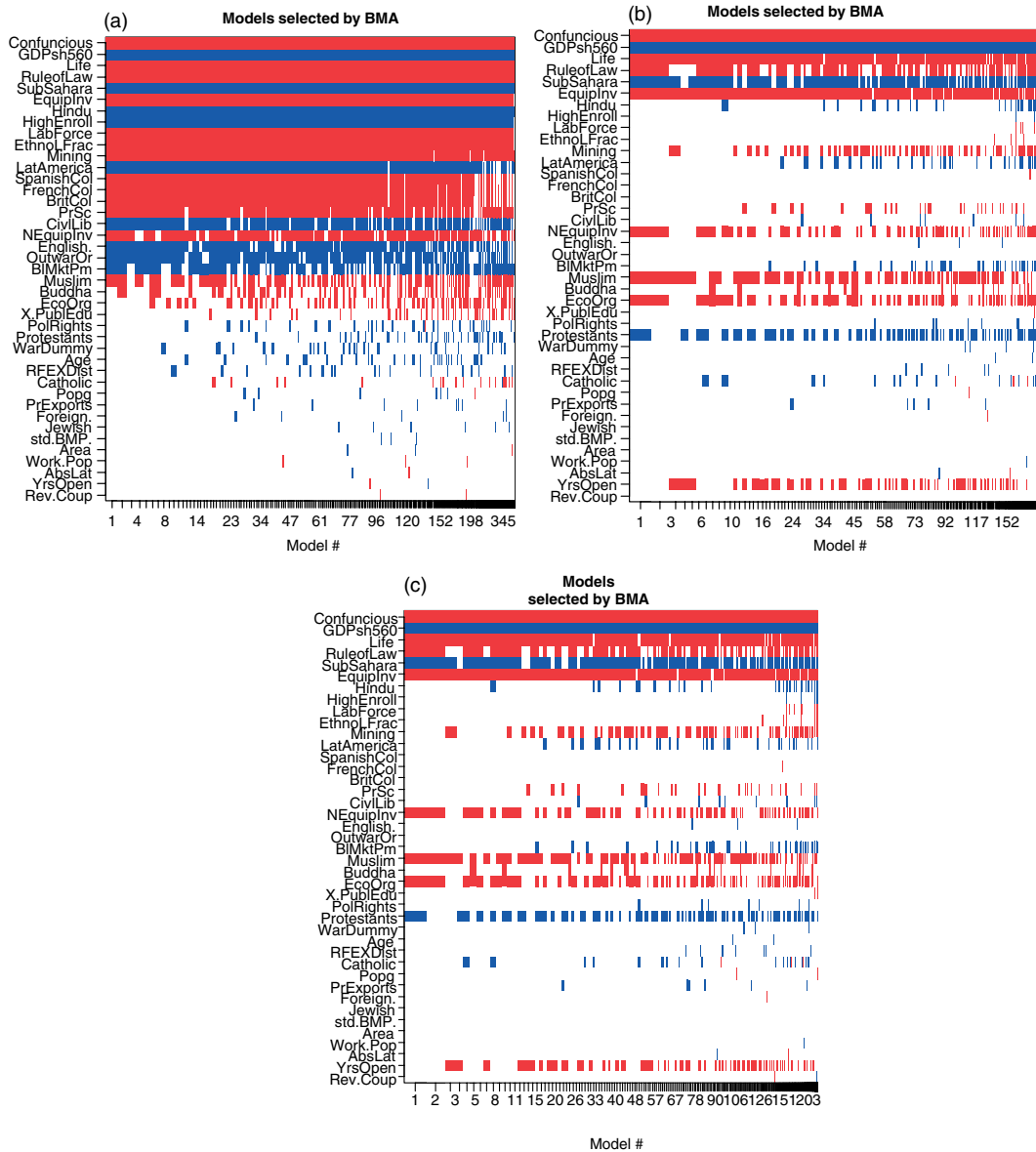


Figure 3. Regressors included in best models. (a) Prior 1 (uniform model prior). (b) Prior 9 (uniform model prior). (c) Prior 1 (prior model size = 7) Note: Posterior means are indicated as positive or negative (darker shading). Horizontal distances indicate posterior model weights. Priors 9 and 10 are identical in the growth context. This figure is available in color online at [wileyonlinelibrary.com/journal/jae](http://wileyonlinelibrary.com/journal/jae)

In summary, candidate default priors differed considerably in dispersion, and led to the choice of different sets of variables. As few as three and as many as 22 regressors were found to be related to growth, depending on the specific prior used.

### 3.3. Assessment of Prior Distributions Using Predictive Performance

We now compare the competing default priors on the basis of predictive performance on hold-out samples, a neutral criterion that allows the comparison of different methods on the same footing. We compare the performance of the full predictive distributions produced by the methods, as well as that of point predictions. Our routine (*bma.compare*, programmed in R and available from the first author on request) simultaneously evaluates all 12 different parameter priors and any specific prior expected model size, as well as their predictive performance.

We divide the dataset randomly into a training set,  $D^T$ , which is used to estimate the BMA predictive distribution, and a hold-out set,  $D^H$ , which is used to assess the quality of the resulting predictive distributions. We use three different criteria, or scoring rules: the mean squared error (MSE) of prediction, the log predictive score (LPS; Good, 1952), and the continuous ranked probability score (CRPS; Matheson and Winkler, 1976). All our scoring rules are negatively oriented, that is, lower is better.

The MSE of prediction is conventionally used to assess the quality of point predictions. The BMA point prediction for an observation in the hold-out dataset,  $y_{\text{new}}$ , with predictors  $x_{\text{new}}$ , is

$$\hat{y}_{\text{new,BMA}} = \sum_{k=1}^K E[y_{\text{new}} | x_{\text{new}}, D^T, M_k] pr(M_k | D^T)$$

The MSE of prediction is then

$$\frac{1}{n_H} \sum_{y_{\text{new}} \in D^H} (y_{\text{new}} - \hat{y}_{\text{new,BMA}})^2$$

where  $n_H$  is the number of observations in  $D^H$ .

The other two scoring rules measure the quality of the predictive distribution as a whole. The BMA predictive distribution is

$$pr_{\text{BMA}}(y_{\text{new}}) = \sum_{k=1}^K pr(y_{\text{new}} | x_{\text{new}}, D^T, M_k) pr(M_k | D^T)$$

The LPS is then defined as

$$\text{LPS} = - \sum_{y_{\text{new}} \in D^H} \log pr_{\text{BMA}}(y_{\text{new}})$$

Let  $F_{\text{BMA}}(y_{\text{new}})$  be the cumulative distribution function corresponding to the BMA predictive density  $pr_{\text{BMA}}(y_{\text{new}})$ . Then the CRPS for the single observation  $y_{\text{new}}$  is

$$\text{CRPS}(y_{\text{new}}) = \int_{-\infty}^{\infty} (F_{\text{BMA}}(y) - 1\{y_{\text{new}} < y\})^2 dy$$

where  $1\{y_{\text{new}} > y\} = 1$  if  $y_{\text{new}} > y$  and 0 otherwise. The CRPS for the hold-out dataset as a whole is then

$$\text{CRPS} = \frac{1}{n_H} \sum_{y_{\text{new}} \in D^H} \text{CRPS}(y_{\text{new}})$$

The CRPS measures the area between a step function at the observed value and the predictive cumulative distribution function. Unlike the LPS, it is defined when the prediction is deterministic; in that case it reduces to the mean absolute error (Hersbach, 2002).

The LPS and the CRPS assess both the sharpness of a predictive distribution and its calibration, namely the consistency between the distributional forecasts and the observations. However, the LPS assigns particularly harsh penalties to poor probabilistic forecasts, and so can be very sensitive to outliers and extreme events (Weigend and Shi, 2000; Gneiting and Raftery, 2007). The CRPS is more robust to outliers (Carney *et al.*, 2009; Gneiting and Raftery, 2007), and hence it is our preferred measure of the performance of the predictive distribution as a whole. We also report the LPS for comparability with previous work, notably that of FLS (2001b) and LS.

We divided the dataset randomly into a training set that contains 80% of the data and thus leaves 20% of the data to be predicted, and we repeated the analysis for 400 different random splits, reporting the average over all splits. Table IV(A) shows the predictive performance of the 12 parameter priors in conjunction with uniform model priors as evaluated by the MSE, LPS and CRPS.

The MSE and the CRPS agree that our baseline Prior 1 decisively outperformed all the other priors. The LPS suggests, however, that Priors 2, 4, 6, and 8 outperform Prior 1. Since this result runs counter to the results from the two other scoring rules, it seems possible that the difference is due to influential observations in the dataset or outliers in a particular subsample. Several of the regressors have extreme outlying values. When such cases are in the test set, they can have a large effect on the LPS, while the CRPS is more robust to individual cases. Given the known outlier sensitivity of the LPS, we discount the results it gives for this dataset, and conclude that Prior 1 performs best in this case.

Table IV(B) compares our results with those of LS (Table V), who did not consider the UIP, but who did include random model priors for parameter Priors 9 and 12, in which a prior distribution was put on the prior inclusion probability  $\pi$ . To achieve an exact comparison with the LS results, Table IV(B) is based on a 85/15 subsample split and we divide our LPS values by the number of held out observations (following LS's LPS formula). In addition, we report absolute log predictive scores (LPS) in Table IV(B) (not values relative to the UIP LPS scores as we do in all of our other tables). Table IV(B) shows that Prior 1 outperformed Priors 9 and 12, whether the model priors are fixed or random.

Recall from Table IV(a) that Prior 1 had better (lower) LPS values than either Prior 9 or Prior 12 with uniform model priors. LS then show that uniform or random model priors generate similar means for Priors 9 and 12. Hence it is no surprise that UIP also has lower LPS values than Priors 9 or 12 with random model priors.

Overall, the unit information prior (Prior 1) with a uniform model prior performed best of the candidate default priors that we have evaluated in terms of cross-validated predictive performance on the growth dataset. Also, the prior expectation of a model size of about seven regressors is not supported by the predictive performance results.

#### 4. SIMULATED DATA

We now examine the effects of the set of priors using simulated datasets from two models that have been prominent in the BMA literature: Model 1 that is based on Raftery *et al.* (1997) and was used by FLS; and Model 2 that is based on George and McCulloch (1993), which was also used by FLS.

Table IV(A). Parameter priors and predictive performance: performance scores *relative* to parameter Prior 1 (growth dataset, model prior: uniform); 400 subsamples

Prior	Mean <sup>a</sup>	Median <sup>a</sup>	% <sup>b</sup>
<i>MSE</i>			
11	0.073	0.014	69***
9	0.075	0.012	69***
6	0.039	0.002	55**
12	0.085	0.006	71***
3	0.083	0.005	69***
4	0.059	0.003	57***
8	0.051	0.003	58***
2	0.022	0.003	58***
5	0.008	0.003	55**
7	0.013	0.004	56***
<i>CRPS</i>			
11	0.854	0.030	69***
9	0.944	0.029	69***
6	0.233	0.005	57***
12	0.675	0.009	65***
3	0.533	0.007	65***
4	0.000	0.002	53
8	0.058	0.003	55**
2	0.193	0.008	58***
5	0.708	0.012	60***
7	1.085	0.018	64***
<i>LPS</i>			
11	0.711	0.711	61***
9	1.078	1.437	63***
6	-1.617	-0.715	41***
12	1.719	1.668	77***
3	1.337	1.348	73***
4	-1.557	-0.780	38***
8	-1.647	-0.846	39***
2	-1.181	-0.435	44***
5	-0.755	0.178	51
7	<b>-0.250</b>	<b>0.731</b>	<b>56***</b>

For Model 1 we generate an  $n \times p$  ( $p = 15$ ) matrix  $R = (r_1, \dots, r_{15})$  of regressors, where the first 10 columns are drawn from independent standard normal distributions, and the next five columns are constructed according to  $(r_{11}, \dots, r_{15}) = (r_1, \dots, r_5) (0.3 \ 0.5 \ 0.7 \ 0.9 \ 1.1)'$   $(1, 1, 1, 1, 1) + E$ , where  $E$  is an  $n \times 5$  matrix of independent standard normal deviates. Model 1 implies small to moderate correlations between the first and last five regressors  $r_1, \dots, r_5$  and  $r_{11}, \dots, r_{15}$ . The correlations increase from 0.153 to 0.561 for  $r_1, \dots, r_5$  and are somewhat larger between the last five regressors, reaching 0.740. Each regressor is centered by subtracting its mean, which results in a matrix  $Z = (z_1, \dots, z_{15})$ . A vector of  $n$  observations is then generated according to

$$\text{Model 1: } 1 : y = 4i_n + 2z_1 - z_5 + 1.5z_7 + z_{11} + 0.5z_{13} + \sigma\varepsilon \tag{10}$$

where the  $n$  elements of  $\varepsilon$  are independent standard normal and  $\sigma = 2.5$ . In Model 1 a third of all the regressors intervene, which we view as fairly typical of some real-world situations, and



Table IV(B). Priors and predictive performance: comparison to Ley and Steel (2007b): absolute performance scores, log predictive score (growth dataset, model prior: uniform); 100 subsamples

Model prior	Fixed, uniform			Random	
	EPR	LS		LS	
Authors					
Parameter prior	1	9	12	9	12
Min.	0.16	1.11	0.86	1.20	1.11
Mean	0.97	1.63	1.65	1.63	1.61
Max.	2.32	2.85	2.76	2.47	2.64
SD	0.47	0.37	0.42	0.25	0.34

*Note:* 100 random split trials (subsamples) and 15% hold-out sample. LS, Ley and Steel (2007b); EPR, Eicher, Papageorgiou, Raftery. Log predictive score: to conform to the Ley and Steel's LPS definition we divide here by the number of held out regressors

we examine datasets with 50 and 100 observations to stay close to the structure of our growth example.

The structure of Model 2 is closer to the growth dataset in terms of numbers of observations and numbers of regressors. It is generated using  $p$  regressors,  $r_i = r_i^* + e$ ,  $i = 1, \dots, p$ , where  $r_i^*$  and  $e$  are  $n$ -dimensional vectors of independent standard normal deviates. This induces a pairwise correlation of 0.5 between all regressors. Let  $Z$  again denote the  $n \times p$  matrix of centered regressors, and generate the  $n$  observations according to

$$\text{Model 2: } y = i_n + \sum_{h=1}^{p/2} z_{(p/2+h)} + \sigma \varepsilon \quad (11)$$

where the  $n$  elements of the error are again independent standard normal and  $\sigma = 2$ . In this simulation model, the second half of the regressors intervene, namely  $(z_{21}, \dots, z_{40})$ .

For Model 1, the differences in the prior variances shown in Figure 4(a)–(c) are similar to the magnitudes observed for the growth dataset in Figure 1. Again about three orders of magnitude separate the most concentrated and most diffuse priors, although the level of concentration is a bit lower in the simulated datasets. Table VI(A) and (B) shows, however, that with well-behaved data all priors basically agree upon which regressors have an effect, even in a dataset that contains only 50 observations. For the larger simulated dataset in Model 2, with about three times the number of candidate regressors as in Model 1, we again find diversity in the number of regressors identified as having an effect on the dependent variable. Table VI(C) shows that several priors are clearly too concentrated, with Priors 2, 5, and 7 identifying only between three and seven of the 20 relevant regressors that in fact had an effect on the dependent variable. As the prior variance increases enough to cover the more substantive part of the likelihood, the priors are able to pick up more of the relevant regressors, getting closer to the correct number of regressors. Priors 3, 9, and 11 pick up 16 candidate regressors, although only Prior 1 shows appropriately high posterior inclusion probabilities.

In summary, our simulation experiment shows that priors can matter, especially when there are many candidate regressors. The UIP is the only one that was robust across simulations, coming closest to identifying the right regressors in all cases.

Table VII shows the UIP's generally superior predictive performance. The MSE was consistently better for the UIP than for all other priors. The LPS was too, except for Prior 3 in Model 2. The

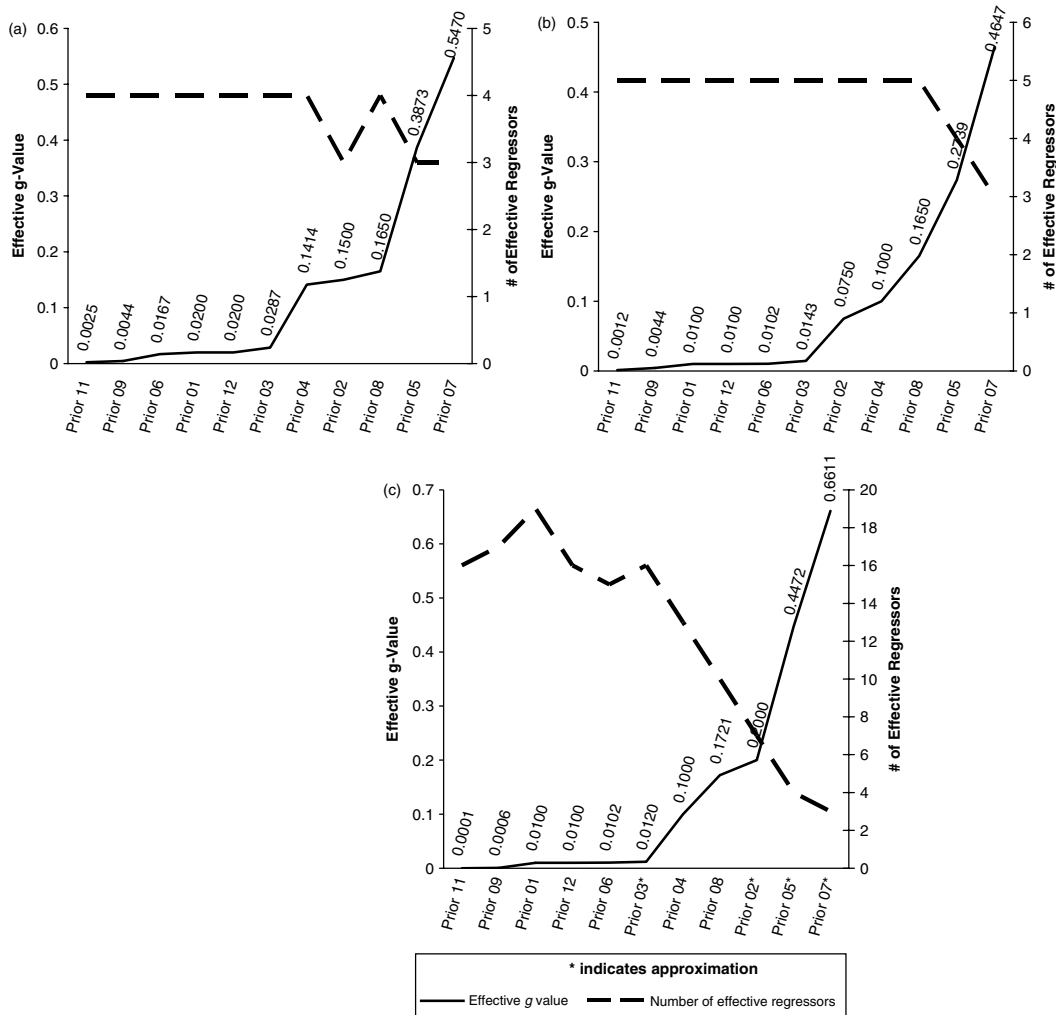


Figure 4. Effective  $g$ -value (inversely related to prior variance) and number of effective regressors (posterior  $> 50\%$ ). (a) Simulated data, Model 1  $k = 15, n = 50$ . (b) Simulated data, Model 1,  $k = 15, n = 100$ . (c) Simulated data, Model 2,  $k = 40, n = 100$ . (1) Priors 9 and 10 are identical in the simulated datasets. (2) Priors 1 and 12 have the same  $g$ -value. (3) Priors are arranged by effective  $g$ -value (increasing left to right). (4) When priors depend on the exact model size,  $p_k$ , (a)–(c) approximate the prior using the expected model size. Priors 11 and 1 are not exact  $g$ -priors, so the  $g$ -value is also an approximation

CRPS preferred the UIP to all other priors for Model 2, but for Model 1 it preferred Priors 3, 4, 6, and 8 to Prior 1.

### 5. CONCLUSION

Model uncertainty is intrinsic in economic analysis and the economic growth literature has been a showcase for model uncertainty over the past decade. Over 140 growth determinants have been

Table V. Parameter priors, model priors, and predictive performance (growth dataset): performance scores *relative to Prior 1 with uniform model prior*; 190 subsamples

	Prior model size = 3		Prior model size = 5		Prior model size = 6		Prior model size = 7		Prior model size = 8		Prior model size = 9		Prior model size = 11		Prior model size = 13		Prior model size = 15		Prior model size = 17			
	Median <sup>a</sup>	% <sup>b</sup>	Median <sup>a</sup>	% <sup>b</sup>	Median <sup>a</sup>	% <sup>b</sup>	Median <sup>a</sup>	% <sup>b</sup>	Median <sup>a</sup>	% <sup>b</sup>	Median <sup>a</sup>	% <sup>b</sup>	Median <sup>a</sup>	% <sup>b</sup>	Median <sup>a</sup>	% <sup>b</sup>	Median <sup>a</sup>	% <sup>b</sup>	Median <sup>a</sup>	% <sup>b</sup>		
	MSE		MSE		MSE		MSE		MSE		MSE		MSE		MSE		MSE		MSE			
11	0.16	71***	0.13	72***	0.14	77***	0.13	71***	0.12	71***	0.16	79***	0.17	81***	0.11	71***	0.10	71***	0.10	71***	0.10	72***
9	0.15	71***	0.12	71***	0.14	78***	0.12	71***	0.12	71***	0.16	81***	0.16	80***	0.11	73***	0.11	74***	0.11	74***	0.10	73***
6	0.09	70***	0.08	71***	0.13	75***	0.09	73***	0.09	72***	0.15	79***	0.12	77***	0.08	80***	0.08	81***	0.08	81***	0.07	79***
1	0.03	67***	0.02	67***	0.02	67***	0.02	69***	0.02	68***	0.04	58***	0.02	69***	0.01	68***	0.01	69***	0.01	69***	0.01	70***
12	0.10	70***	0.08	71***	0.13	75***	0.09	72***	0.09	73***	0.15	80***	0.12	78***	0.08	82***	0.08	81***	0.07	81***	0.07	81***
3	0.09	70***	0.08	71***	0.13	75***	0.09	73***	0.09	72***	0.15	79***	0.12	77***	0.08	80***	0.08	81***	0.07	79***	0.07	79***
4	0.08	68***	0.06	67***	0.09	70***	0.05	65***	0.05	65***	0.13	78***	0.11	76***	0.06	69***	0.06	73***	0.05	73***	0.05	73***
8	0.09	67***	0.08	65***	0.09	68***	0.05	65***	0.05	65***	0.13	74***	0.12	76***	0.05	66***	0.05	71***	0.05	71***	0.05	71***
2	0.09	67***	0.07	68***	0.10	70***	0.07	68***	0.06	67***	0.12	74***	0.14	76***	0.05	63***	0.06	65***	0.05	65***	0.05	65***
5	0.15	70***	0.13	69***	0.15	76***	0.11	67***	0.11	67***	0.17	73***	0.17	77***	0.09	65***	0.09	64***	0.08	64***	0.08	65***
7	0.19	75***	0.17	73***	0.18	80***	0.16	73***	0.15	72***	0.20	75***	0.20	80***	0.13	69***	0.12	69***	0.10	69***	0.10	68***

	CRPS		CRPS		CRPS		CRPS		CRPS		CRPS		CRPS		CRPS		CRPS		CRPS		CRPS	
	Median <sup>a</sup>	% <sup>b</sup>	Median <sup>a</sup>	% <sup>b</sup>	Median <sup>a</sup>	% <sup>b</sup>	Median <sup>a</sup>	% <sup>b</sup>	Median <sup>a</sup>	% <sup>b</sup>	Median <sup>a</sup>	% <sup>b</sup>	Median <sup>a</sup>	% <sup>b</sup>	Median <sup>a</sup>	% <sup>b</sup>	Median <sup>a</sup>	% <sup>b</sup>	Median <sup>a</sup>	% <sup>b</sup>	Median <sup>a</sup>	% <sup>b</sup>
11	0.04	83***	0.04	80***	0.03	78***	0.03	79***	0.02	77***	0.03	72***	0.05	78***	0.01	77***	0.01	72***	0.01	72***	0.01	71***
9	0.04	85***	0.03	77***	0.02	79***	0.02	79***	0.02	75***	0.02	71***	0.04	75***	0.01	73***	0.01	74***	0.01	74***	0.01	71***
6	0.01	69***	0.01	66***	0.01	69***	0.01	66***	0.01	67***	0.01	62***	0.01	63***	0.00	71***	0.00	62***	0.00	62***	0.00	63***
1	0.00	61***	0.00	59***	0.00	62***	0.00	61***	0.00	61***	0.01	53	0.00	59***	0.00	57***	0.00	57***	0.00	57***	0.00	55***
12	0.02	73***	0.01	68***	0.01	71***	0.01	71***	0.01	69***	0.01	62***	0.01	63***	0.00	68***	0.00	65***	0.00	65***	0.00	68***
3	0.01	69***	0.01	66***	0.01	69***	0.01	66***	0.01	67***	0.01	62***	0.01	63***	0.00	71***	0.00	62***	0.00	62***	0.00	63***
4	0.01	67***	0.00	56*	0.00	59**	0.00	56*	0.00	53	0.01	59**	0.00	53	0.00	59**	0.00	57**	0.00	57**	0.00	57**
8	0.01	65***	0.00	57**	0.00	59**	0.00	56*	0.00	56*	0.00	55***	0.00	56**	0.00	53	0.00	55	0.00	55	0.00	56*
2	0.01	72***	0.01	66***	0.01	66***	0.00	58**	0.00	57**	0.01	61***	0.01	65***	0.00	53	0.00	54	0.00	54	0.00	52
5	0.01	65***	0.01	65***	0.00	63***	0.00	61***	0.00	61***	0.01	59**	0.01	57***	0.00	55	0.00	51	0.00	51	0.00	51
7	0.01	63***	0.01	58**	0.00	60***	0.00	59**	0.00	62***	0.01	60***	0.01	57***	0.00	55*	0.00	52	0.00	52	0.00	51



Table VI(A). Posterior inclusion probabilities across parameter priors: simulated data, Model1,  $k = 15$ ,  $n = 50$ ; priors arranged by effective  $g$ -value (increasing left to right)

Regressor	11	9	6	1	12	3	4	2	8	5	7
$z_1$	<b>100</b>	<b>100</b>	<b>100</b>	<b>100</b>	<b>100</b>	<b>100</b>	<b>100</b>	<b>100</b>	<b>100</b>	<b>99.9</b>	<b>99.5</b>
$z_7$	<b>100</b>	<b>100</b>	<b>99.3</b>	<b>100</b>	<b>100</b>	<b>100</b>	<b>99.8</b>	<b>99.2</b>	<b>99.6</b>	<b>94.4</b>	<b>90.9</b>
$z_{11}$	<b>99.6</b>	<b>99.6</b>	<b>96.9</b>	<b>99.9</b>	<b>99.7</b>	<b>99.7</b>	<b>98.6</b>	<b>95.6</b>	<b>97.9</b>	<b>84.3</b>	<b>79</b>
$z_5$	<b>70</b>	<b>67</b>	<b>65.5</b>	<b>73.7</b>	<b>70.5</b>	<b>71.2</b>	<b>67.8</b>	46.2	<b>65.1</b>	36.9	34.5
$z_2$	18.5	23.6	37.3	34.9	32.2	34.9	37	20.9	35.7	22.6	22.3
$z_4$	19.9	23.1	36.7	32.9	30.7	33.2	35.8	22.1	34.9	26	26.3
$z_{14}$	18.8	13.8	32.5	27.4	23.4	26.8	31.1	11.2	29.2	14.7	15.9
$z_9$	10.6	8.7	31.3	20	16.7	20.1	28.2	8.8	26.3	11.4	12.5
$z_3$	9	9.3	29.2	21.7	18.1	21.5	27.3	8.4	25.4	11.4	12.5
$z_{13}$	10.7	7.5	22.1	14.1	12.5	14.4	19.6	7.7	18.6	11	12.4
$z_{12}$	10.2	8.9	20.2	15	13.6	15.2	18.6	8.2	17.7	10.5	11.3
$z_8$	6.7	5.3	18.1	9.5	8.7	10.1	15.2	7.2	14.7	11.2	12.6
$z_{15}$	6.4	6.1	15.3	9.7	9.1	10.3	13.5	6.3	13.1	7.8	8.4
$z_6$	5.1	4.2	7.3	4.9	5.1	5.4	6.4	5.2	6.5	6.8	7.2
$z_{10}$	5.2	4.4	7.1	4.9	5.2	5.4	6.3	5.3	6.4	7.1	7.5
# effects	4	4	4	4	4	4	4	3	4	3	3

Table VI(B). Posterior inclusion probabilities across parameter priors. simulated data: Model 1,  $k = 15$ ,  $n = 100$ ; priors arranged by effective  $g$ -value (increasing left to right)

Regressor	11	9	1	12	6	3	2	4	8	5	7
$z_1$	<b>100</b>	<b>100</b>	<b>100</b>	<b>100</b>	<b>100</b>	<b>100</b>	<b>100</b>	<b>100</b>	<b>100</b>	<b>100</b>	<b>100</b>
$z_7$	<b>100</b>	<b>100</b>	<b>100</b>	<b>100</b>	<b>100</b>	<b>100</b>	<b>100</b>	<b>100</b>	<b>100</b>	<b>99.6</b>	<b>97.9</b>
$z_{11}$	<b>99.4</b>	<b>99.4</b>	<b>99.7</b>	<b>99.5</b>	<b>99.5</b>	<b>99.5</b>	<b>97.6</b>	<b>99.1</b>	<b>98.1</b>	<b>86.5</b>	<b>75.6</b>
$z_5$	<b>92.9</b>	<b>92.9</b>	<b>95.6</b>	<b>94.5</b>	<b>94.5</b>	<b>94.9</b>	<b>83.8</b>	<b>93.9</b>	<b>90.5</b>	<b>57.6</b>	43.6
$z_{15}$	<b>79.9</b>	<b>81.1</b>	<b>87.8</b>	<b>85</b>	<b>85.1</b>	<b>86.2</b>	<b>63.2</b>	<b>85.1</b>	<b>78.8</b>	35.8	28.3
$z_6$	15.6	15.4	22.1	21.2	21.3	23.7	14.9	39	38	13	12.3
$z_{12}$	13.7	13.2	19.2	18.3	18.4	20.5	12.4	33.2	32.2	10.9	10.4
$z_4$	134.3	15.8	17.3	17.9	18	19.1	23	27.5	29.7	33.6	34.2
$z_{13}$	7.7	6.9	9.9	9.7	9.7	10.9	7.1	16.7	16.6	7.9	8.8
$z_{10}$	4.8	5.1	7.9	7.6	7.6	8.7	5.2	17.7	17.8	5.3	5.4
$z_3$	4	6.1	7.4	7.6	7.6	8.3	7.7	12.3	13.1	9.1	8.7
$z_2$	3.2	5	7	6.9	6.9	7.8	5.4	13.2	13.4	5.9	5.9
$z_8$	6	5.6	7	7	7.1	7.7	6.4	11	11.3	7.4	7.7
$z_9$	4.9	4.6	6.8	6.6	6.7	7.6	4.9	14.3	14.4	5.2	5.2
$z_{14}$	4.6	4.3	6	5.9	6	6.7	4.6	10.9	11.1	5	5.3
# effects	5	5	5	5	5	5	5	5	5	4	3

motivated by the empirical literature, and the number of competing theories has grown dramatically since the advent of the New Growth Theory. Bayesian model averaging (BMA) provides a solid theoretical foundation for addressing model uncertainty as part of the empirical strategy.

However, BMA faces an important challenge. In this paper we showed that for a well-known growth dataset the results of BMA were sensitive to the prior specification. To identify the best prior for our growth dataset, we examined the predictive performance of 12 candidate default parameter priors that have been proposed in the statistics and economics literatures, as well as several model priors that have been advocated. We argue that predictive performance is a natural and neutral criterion for comparing different priors, and suggest the CRPS as a preferred measure. In addition, we examined these priors' success in identifying the right determinants in simulated datasets.

Table VI(C). Posterior inclusion probabilities across parameter priors: simulated data, Model 2,  $k = 40$ ,  $n = 100$ ; priors arranged by effective  $g$ -value (increasing left to right)

Regressor	11	9	1	12	6	3	4	8	2	5	7
Z <sub>1</sub>	1.5	1.8	2.8	2.4	2	2.7	0.8	1.3	0.8	2.1	2
Z <sub>2</sub>	0.9	1.2	8.6	1.7	1.5	2	0.2	0.1	0	0	0
Z <sub>3</sub>	4.1	4.8	13.9	4.9	4.5	5.6	0.4	0.2	0	0.4	0.9
Z <sub>4</sub>	0.6	0.6	1.6	1.1	1.3	1.2	0.1	0	0	1	2.1
Z <sub>5</sub>	0.3	0.4	1.9	0.8	0.5	0.9	0.2	0.6	0.7	0.2	0.1
Z <sub>6</sub>	0.4	0.5	3.9	1	0.5	1.1	0.1	0	0	0	0
Z <sub>7</sub>	0.3	0.3	1.5	0.8	0.1	0.9	0.2	0.5	0.9	0.5	0.3
Z <sub>8</sub>	0.4	0.6	4.5	1	0.1	1.1	0.1	0.1	0.1	1	1.1
Z <sub>9</sub>	0.3	0.4	2.5	0.8	0.5	0.9	0.1	0	0	0	0
Z <sub>10</sub>	0.4	0.4	1.6	0.9	0.6	0.9	0.1	0	0.1	1.3	1.9
Z <sub>11</sub>	6.1	6.7	14.3	6.1	6.2	6.8	0.5	0.2	1.2	6.3	7
Z <sub>12</sub>	10.7	14.2	33.2	11.7	10.7	13.2	1.8	0.7	0	0	0
Z <sub>13</sub>	0.3	0.4	3	0.9	0.6	1	0.1	0	0	0	0.2
Z <sub>14</sub>	12.7	12.6	6.8	15.7	14.7	16	12	7.8	0.5	0.4	0.2
Z <sub>15</sub>	0.4	0.5	3.9	0.9	0.1	1.1	0.1	0	0	0	0.1
Z <sub>16</sub>	1.5	1.8	4.9	2.1	2.3	2.4	0.2	0.1	0	0.6	1.2
Z <sub>17</sub>	0.5	0.6	2.5	1	1	1.1	0.2	0.4	0.4	2.6	3.4
Z <sub>18</sub>	10.4	10.6	7.1	8.8	9.6	9.3	14.7	22.4	29.9	23.7	17.8
Z <sub>19</sub>	0.8	1	6.1	1.4	1.3	1.7	1.4	3.6	9.3	10.6	9
Z <sub>20</sub>	0.6	0.7	2.7	1.2	1.4	1.3	1.7	1.5	1.9	1.2	1.2
Z <sub>21</sub>	4.4	7	<b>57.1</b>	4.2	4	5.3	0.4	0.9	2.1	1	0.6
Z <sub>30</sub>	35.3	41.9	<b>94</b>	26.5	26.5	30	3.8	1.5	0	0.4	1.1
Z <sub>38</sub>	44.6	<b>50.9</b>	<b>95.9</b>	38.4	38.4	41.2	20.1	11.9	1.3	0.6	0.3
Z <sub>33</sub>	<b>98.7</b>	<b>99</b>	<b>100</b>	<b>93.3</b>	<b>93.2</b>	<b>93.7</b>	38.2	19.8	0.5	3.8	5.3
Z <sub>22</sub>	<b>72.2</b>	<b>75.4</b>	<b>98.6</b>	<b>50.9</b>	49.7	<b>54.8</b>	7.4	9.1	21.8	40.4	45.2
Z <sub>25</sub>	<b>99.7</b>	<b>99.8</b>	<b>100</b>	<b>96.8</b>	<b>96.6</b>	<b>97.1</b>	29.1	14.7	1.1	1.1	0.8
Z <sub>27</sub>	<b>100</b>	<b>100</b>	<b>100</b>	<b>99.3</b>	<b>99.4</b>	<b>99.3</b>	<b>64.5</b>	39.4	0.9	0.3	0.3
Z <sub>32</sub>	<b>99</b>	<b>99.3</b>	<b>100</b>	<b>94.2</b>	<b>93.8</b>	<b>94.7</b>	<b>50.8</b>	30.9	1.3	1	1.4
Z <sub>35</sub>	<b>100</b>	<b>100</b>	<b>100</b>	<b>100</b>	<b>100</b>	<b>100</b>	<b>72.5</b>	45.7	2.6	2.7	2.9
Z <sub>23</sub>	<b>100</b>	<b>100</b>	<b>100</b>	<b>100</b>	<b>100</b>	<b>100</b>	<b>81.9</b>	<b>56.9</b>	3.1	2	2.3
Z <sub>37</sub>	<b>100</b>	<b>100</b>	<b>100</b>	<b>100</b>	<b>100</b>	<b>100</b>	<b>83.1</b>	<b>57.8</b>	4.6	1.6	1.1
Z <sub>39</sub>	<b>100</b>	<b>100</b>	<b>100</b>	<b>100</b>	<b>100</b>	<b>100</b>	<b>97.3</b>	<b>86.7</b>	31	13.4	10.4
Z <sub>31</sub>	<b>100</b>	<b>100</b>	<b>100</b>	<b>99.4</b>	<b>99.5</b>	<b>99.4</b>	<b>77.4</b>	<b>79</b>	<b>67.6</b>	45.7	35.2
Z <sub>29</sub>	<b>100</b>	<b>100</b>	<b>100</b>	<b>100</b>	<b>100</b>	<b>100</b>	<b>99.9</b>	<b>98.7</b>	<b>78.3</b>	37.3	24.6
Z <sub>24</sub>	<b>100</b>	<b>100</b>	<b>100</b>	<b>100</b>	<b>100</b>	<b>100</b>	<b>99.4</b>	<b>95</b>	<b>55.7</b>	26.6	19.9
Z <sub>36</sub>	<b>100</b>	<b>100</b>	<b>100</b>	<b>100</b>	<b>100</b>	<b>100</b>	<b>80.7</b>	<b>61.4</b>	28.4	19.6	14
Z <sub>28</sub>	<b>100</b>	<b>100</b>	<b>100</b>	<b>100</b>	<b>100</b>	<b>100</b>	<b>99.9</b>	<b>99.2</b>	<b>90.2</b>	<b>64.5</b>	<b>50.5</b>
Z <sub>26</sub>	<b>99</b>	<b>99.2</b>	<b>100</b>	<b>92.7</b>	<b>93.5</b>	<b>93.3</b>	<b>55.8</b>	<b>66.7</b>	<b>82.2</b>	<b>85.6</b>	<b>86.1</b>
Z <sub>40</sub>	<b>100</b>	<b>100</b>	<b>100</b>	<b>99.5</b>	<b>99.4</b>	<b>99.5</b>	<b>85.1</b>	<b>89.3</b>	<b>100</b>	<b>95.3</b>	<b>86.8</b>
# effects	16	17	19	16	15	16	13	10	6	3	3

Note: Shaded variables should have an effect. Posterior inclusion probabilities that exceed 50% are in bold font (Jeffreys, 1961). Priors 9 and 10 are identical in the simulated datasets. Uniform model priors throughout. Priors arranged by effective  $g$ -value.

The UIP performed better than the other 11 priors in the growth data, and in simulated data, and as measured by our preferred median CRPS scoring rule. The UIP together with the uniform model prior also performed better than the Mitchell–Beauchamp model prior with expected model size 7, which had previously been recommended by Sala-i-Martin *et al.* (2004). We view the UIP with the uniform model prior as a reasonable default prior and starting place, but our results also highlight that researchers should also assess other possibilities that may be more appropriate for their data and applications.

Table VII. Predictive performance relative to parameter Prior 1 for the three simulated datasets: uniform model prior; 400 subsamples

(a) Model 1, $k = 15, n = 50$				(b) Model 1, $k = 15, n = 100$				(c) Model 2, $k = 40, n = 100$			
Prior	Mean <sup>a</sup>	Median <sup>a</sup>	% <sup>b</sup>	Prior	Mean <sup>a</sup>	Median <sup>a</sup>	% <sup>b</sup>	Prior	Mean <sup>a</sup>	Median <sup>a</sup>	% <sup>b</sup>
MSE				MSE				MSE			
11	0.004	0.003	55**	11	0.114	0.120	70***	11	0.010	0.007	90***
9	0.003	0.002	56**	9	0.127	0.127	71***	9	0.007	0.006	90***
6	0.029	0.026	67***	6	1.689	2.041	85***	6	0.027	0.026	75***
12	0.000	0.001	55**	12	0.019	0.057	61***	12	0.003	0.003	79***
3	0.000	0.000	52	3	-0.015	0.043	56**	3	0.002	0.001	64***
8	0.010	0.008	59***	8	1.025	1.303	77***	8	0.018	0.017	71***
4	0.009	0.007	59***	4	0.467	0.697	69***	4	0.008	0.007	62***
2	0.015	0.010	60***	2	0.398	0.668	70***	2	0.026	0.022	84***
5	0.064	0.054	75***	5	2.541	2.802	90***	5	0.063	0.059	88***
7	0.097	0.088	79***	7	4.116	4.440	94***	7	0.105	0.097	93***
CRPS				CRPS				CRPS			
11	0.021	0.007	72***	11	0.015	0.007	80***	11	-0.011	-0.002	47
9	0.010	0.004	69***	9	0.016	0.008	82***	9	-0.012	0.000	50
6	-0.002	-0.001	42***	6	-0.012	-0.005	27***	6	0.031	0.014	76***
12	0.000	0.000	47	12	-0.001	0.000	46*	12	0.001	0.001	54*
3	-0.001	-0.001	42***	3	-0.005	-0.003	26***	3	0.006	0.002	57***
8	-0.002	-0.001	42***	8	-0.012	-0.005	25***	8	0.028	0.013	73***
4	-0.002	-0.002	41***	4	-0.012	-0.006	23***	4	0.028	0.012	71***
2	0.001	0.001	54*	2	-0.002	0.000	48	2	0.001	0.004	58**
5	0.001	0.001	54*	5	-0.010	-0.003	33***	5	0.022	0.013	71***
7	0.002	0.002	57***	7	-0.009	-0.003	38***	7	0.027	0.016	74***
LPS				LPS				LPS			
11	0.022	0.057	56**	11	0.114	0.120	70***	11	0.443	0.463	81***
9	0.044	0.053	55**	9	0.127	0.127	71***	9	0.279	0.331	79***
6	1.076	1.542	76***	6	1.689	2.041	85***	6	3.885	2.734	77***
12	-0.091	0.030	52	12	0.019	0.057	61***	12	-0.418	0.016	51
3	-0.114	0.049	56**	3	-0.015	0.043	56**	3	-0.543	-0.092	45**
8	0.414	0.817	71***	8	1.025	1.303	77***	8	2.955	1.872	73***
4	0.374	0.768	71***	4	0.467	0.697	69***	4	1.784	0.954	67***
2	0.428	0.849	70***	2	0.398	0.668	70***	2	2.824	1.475	76***
5	1.823	2.330	84***	5	2.541	2.802	90***	5	5.782	4.274	87***
7	2.453	2.962	87***	7	4.116	4.440	94***	7	7.684	6.124	92***

<sup>a</sup> Refers to the improvement in the score attained by the UIP compared to a given alternative prior.

<sup>b</sup> Indicates percent of trials where 'success' is a better predictive score by the UIP than by the alternative prior. Asterisks indicate \*\*\* 99%, \*\* 95%, and \* 90% significance levels based on binomial  $p$ -values,  $P(X \geq z)$ , for the given number of trials and successes, where success is defined as a better score for prior 1 (the alternative) as compared to the alternative prior (UIP) if the percentage is above (below) 50%.

Note: Priors 9 and 10 are identical in the simulated dataset

We have focused here on priors where  $\pi$  and  $g$  are fixed. A Bayesian alternative is to put prior distributions on  $\pi$  and  $g$  themselves and integrate them out. Ley and Steel (2009) advocated putting a prior distribution on  $\pi$  but their results did not show that this led to improved predictive

performance, as we have seen. Liang *et al.* (2008) reviewed a range of parameter priors that put a prior on  $g$  and integrate it out (they called them mixtures of  $g$ -priors). They assessed predictive performance in one example using only the highest probability model under each prior rather than BMA, and reported only the MSE of prediction, and not any measure of the performance of the full predictive distribution. They concluded that the differences in MSE were not enough to suggest that the mixtures of  $g$ -priors performed better than the fixed  $g$  methods. It would be interesting to see a more complete assessment of these methods in terms of predictive performance.

In terms of economic impact, the UIP with uniform model prior identified more growth determinants than Fernández *et al.* (2001b), who used the same dataset. The additional regressors include Primary and Secondary Education, Size of Labor Force, Ethnolinguistic Fragmentation, Minging, Latin America, Colonies (British, French, Spanish), Civil Liberties, Non Equipment Investment, Black Market Premium, Outward Orientation and Fraction Speaking English and Hindu.

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